

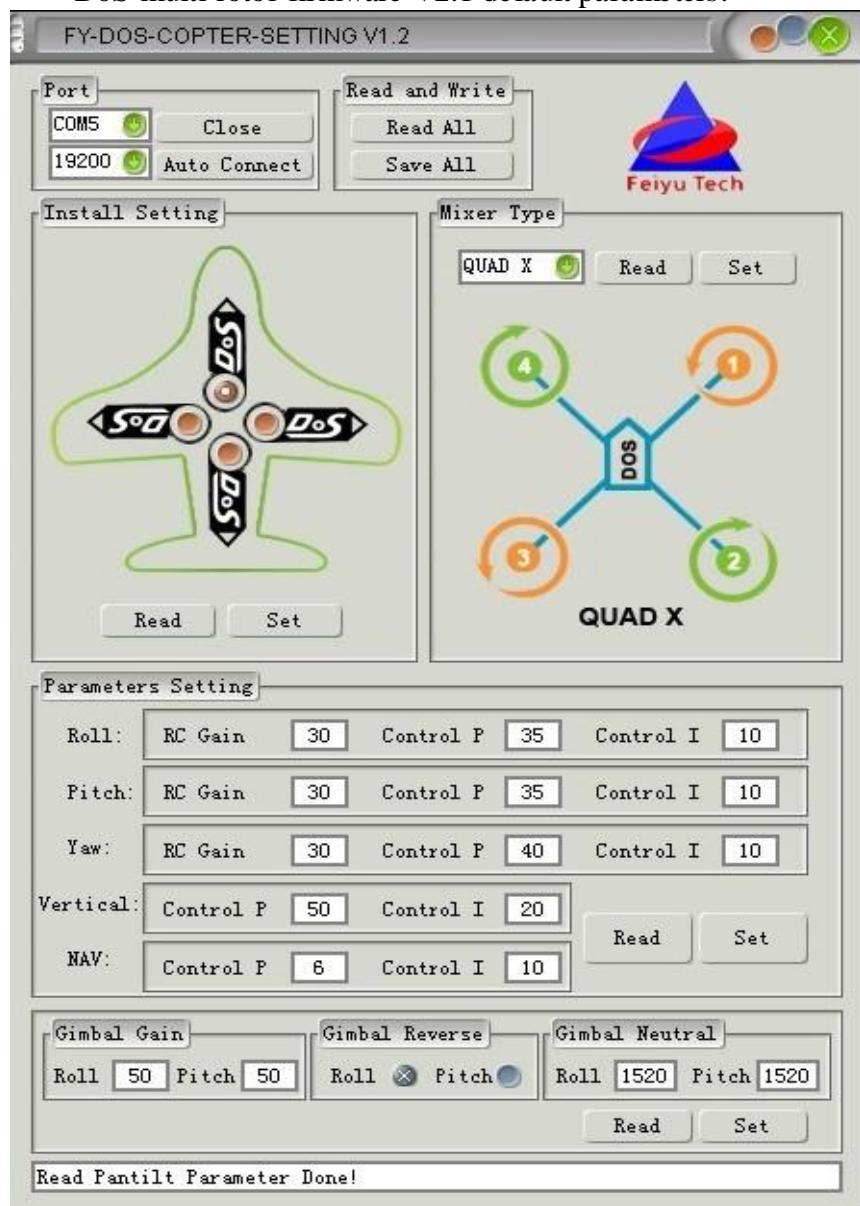
## Announcements about upgrade DoS multi-rotor firmware V 2.1

### Firmware V2.1 Update Log:

- 1、Add GPS Hovering mode and Auto Return To Launch (RTL) mode
- 2、To improve the fixed altitude flight effect

DoS firmware V2.1 add the GPS function and Camera Gimbal Stabilization control function, so the “FY-DOS-COPTER-SETTING V1.2” software add the Navigation control and Camera Gimbal Stabilization control parameters. Please noticed that, when you upgrade firmware to V2.1 from V2.0, you should set these two parameters to default before any flight test. (But upgarde firmware V2.1 from fixed wing aircraft firmware all the parameters will automatic set to default)

DoS multi-rotor firmware V2.1 default parameters:



**Please set the navigation control and Camera Gimbal Stabilization control parameters to default:**

(1) Navigation control parameters

NAV:	Control P	6	Control I	10
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(2) Camera Gimbal Stabilization control parameters

Gimbal Gain Roll 50 Pitch 50	Gimbal Reverse Roll <input checked="" type="radio"/> Pitch <input checked="" type="radio"/>	Gimbal Neutral Roll 1520 Pitch 1520
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